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Probabilistic robotics is a subfield of robotics concerned with the perception and control part. It relies on statistical techniques for representing information and making decisions. By doing so, it accommodates the uncertainty that arises in most contemporary robotics applications.

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Since the mid-1990s, a new approach has begun to emerge: probabilistic robotics. This approach relies on statistical techniques to seamlessly integrate imperfect models and imperfect sensing. The present article describes the basics of probabilistic robotics and highlights some of its recent successes.

Sebastian Thrun's Homepage

Chapter 2 Basis of probabilistic robotics T his chapter will introduce the basis of probabilistic robotics used by the methods presented in this work.

Chapter 2 Basis of probabilistic robotics

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